The diagram illustrates the relationship between estimation error and various conditions. The Y-axis represents estimation error, while the X-axis shows different conditions including ideal conditions and real conditions. The conditions include:

- Noise coloration
- Noise nonstationarity
- Measurement uncertainty
- Model uncertainty

Two curves are shown: one for Kalman and another for OUFIR. As the conditions deviate from ideal to real, the estimation error increases significantly for both methods.

Delta (Δ) represents the change in estimation error as conditions change.