Figure 3.

A) $myo1\Delta$  

\[
\begin{array}{c|c}
myo1\Delta & tor1\Delta \\
myo1\Delta & \\

\hline
Npr1p & \\
PgL1p & \\
\end{array}
\]

B) $myo1\Delta$  

\[
\begin{array}{c|c}
myo1\Delta & sit4\Delta \\
myo1\Delta & \\

\hline
Npr1p^\# & \\
Npr1p & \\
PgL1p & \\
\end{array}
\]