

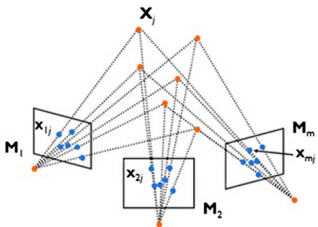
1 Feature detection and extraction



2 Feature matching



3 Structure-from-Motion



Recover position of 3D points (X_j) and camera matrices* (M_1, \dots, M_m) using correspondences between feature points in the images (x_{1j}, \dots, x_{mj})